

**PHYSICAL PROTOTYPE OF AN AUTONOMOUS BUOY FOR
TRACKING SPILLED OIL**

YUSRINA BINTI ABDULLAH

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2013

**FACULTY OF MARITIME STUDIES AND
MARINE SCIENCE
UNIVERSITI MALAYSIA TERENGGANU
2013**

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Perpustakaan Sultanah Nur Zahirah
Universiti Malaysia Terengganu (UMT)

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Physical prototype of an autonomous buoy for tracking oil spill /
Yusrina Abdullah.



PERPUSTAKAAN SULTANAH NUR ZAHIRAH
UNIVERSITI MALAYSIA TERENGGANU (UMT)
21030 KUALA TERENGGANU.

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PERPUSTAKAAN SULTANAH NUR ZAHIRAH UTM

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**PHYSICAL PROTOTYPE OF AN AUTONOMOUS BUOY FOR
TRACKING OIL SPILL**

By

YUSRINA BINTI ABDULLAH

**A thesis submitted in partial fulfilment of
the requirement for the award of the degree of
Bachelor of Applied Science (Maritime Technology)**

**DEPARTMENT OF MARITIME TECHNOLOGY
FACULTY OF MARITIME STUDIES AND SCIENCE MARINE
UNIVERSITI MALAYSIA TERENGGANU**

2013



**DEPARTMENT OF MARITIME TECHNOLOGY
FACULTY OF MARITIME STUDIES AND MARINE SCIENCE
UNIVERSITI MALAYSIA TERENGGANU**

**DECLARATION AND VERIFICATION REPORT
FINAL YEAR RESEARCH PROJECT**

It is hereby declared and verified that this research report entitled: **PHYSICAL PROTOTYPE OF AN AUTONOMOUS BUOY FOR TRACKING OIL SPILL** by **YUSRINA BINTI ABDULLAH**, Matric No. **UK 20722** has been examined and all errors identified have been corrected. This report is submitted to the Department of Maritime Technology as partial fulfillment towards obtaining the **Bachelor Degree of Applied Science (Maritime Technology)**, Faculty of Maritime Studies and Marine Science, Universiti Malaysia Terengganu.

Verified by:

.....

Principal Supervisor

Name: Dr. AHMAD FAISAL bin MOHAMAD AYOB

Official stamp:

DR. AHMAD FAISAL MOHAMAD AYOB
LECTURER
DEPARTMENT OF MARITIME TECHNOLOGY
FACULTY OF MARITIME STUDIES AND MARINE SCIENCE
UNIVERSITI MALAYSIA TERENGGANU (UMT)
21030 KUALA TERENGGANU

Date: 10/11/2013

Second Supervisor

Name: Dr. AHMAD FITRIADHY

Official stamp:

DR. ENG. AHMAD FITRIADHY
LECTURER
DEPARTMENT OF MARINE TECHNOLOGY
FACULTY OF MARITIME STUDIES AND MARINE SCIENCE
UNIVERSITI MALAYSIA TERENGGANU (UMT)
21030 KUALA TERENGGANU

Date: 13/01/2013

Head of Department of Maritime Technology
Name: Assoc. Prof. Dr. MOHAMMAD FADHLI bin AHMAD

Official stamp:

Date: 16/1/13

ASSOC.PROF. DR. MOHAMMAD FADHLI AHMAD
HEAD
DEPARTMENT OF MARITIME TECHNOLOGY
FACULTY OF MARITIME STUDIES AND MARINE SCIENCE
UNIVERSITI MALAYSIA TERENGGANU (UMT)
21030 KUALA TERENGGANU

DECLARATION

I hereby declare that this thesis entitled Development of Laboratory Scale Remote Operated Vehicle for Marine Applications is the result of my own research except as cited in the references.

Signature :

Name : Yusrina Binti Abdullah

Matric No. : UK 20722

Date :

ACKNOWLEDGEMENTS

In the name of Allah most gracious and most merciful. Thanks to Allah with his bless I can finish this report of final year project which is one of the qualified in order to graduate in this bachelor applied science of Maritime technology.

In order to finish this report, I have to get the cooperation, contributions and assistance in terms of advice, moral and spiritual support, and also technical assistance from various parties because this is actually new experience for me. Before this, I only learnt the theoretical and lack of understanding the technical. With this project, it makes me understand more about this topic.

I would like to thank all those people who made this thesis possible and an enjoyable experience for me. First of all, I would like to express my sincere gratitude to my supervisor, Dr.Ahmad Faisal Mohamad Ayob and my second supervisor, Dr. Ahmad Fitriady on their guidance, inducement and also constructive criticism given along the period until this thesis is completed.

I am grateful to all my friends and coursemates especially Mohd Tareq Ziad, Ainun Naeimah, Norhayati, Akmal Nawawi, Kharee Ibrahim and Nor Hasnaa' Kamilah for their encouragement and help. My friends had made available their full support in a number of ways. I'm grateful for their insight comments and continuous support. I'm also grateful to the Department of Maritime Technology and Maritime Technology laboratory for their guidance and help in accomplishing my project.

Last but not least, I would like to express my deepest gratitude for a constant support, emotional understanding and love that I received from my family especially to my beloved father, Abdullah Ahmad , mother, Faridah bt Abdullah and also my siblings. Sometimes when I fell like down, they always become my spirit to finish up all of this things. Without their support, I would not have completed my research successfully.

PYHICAL PROTOTYPE OF AN AUTONOMOUS BUOY FOR TRACKING OIL SPILL

ABSTRACT

Marine pollution by oil spill caused environmental hazards, this problem requires a low-cost system for the detection of oil spills efficiently and able to provide accurate warnings when the accident happened. Such a system is necessary to control the spread of oil and speed up the cleaning process. The tools that have been developed previously unable to meet the criteria as effectively tracking spilled oil. So, the method and the new system should be brought to the detection of oil spills. This project presents a buoy equipped with sensors that use copper and is able to detect and transmit information at the time of the accident spilled oil and its installation is easy. The paper discusses the development and analysis of buoy and sensor concept. The application of electrolysis applied on the sensor, which are based on the electric conductivity properties of oil and water. The application concept of electrolysis for sensor is assisted with Arduino UNO programme . The results presented in this paper, which are physical prototype and the performance of sensor proposed to detect the oil spilled in real testing.

PROTOTAIP FIZIKAL BOYA BERANATOMI UNTUK MENGESAN MINYAK TERTUMPAH

ABSTRAK

Pencemaran laut oleh tumpahan minyak menyebabkan terganggunya ekosistem hidupan aquatik, masalah ini memerlukan sistem yang berkos rendah dan cekap untuk pengesanan minyak tumpah dan mampu memberi amaran tepat ketika kemalangan ini berlaku. Sistem sebegini adalah perlu untuk mengawal daripada minyak merebak dan mempercepatkan proses pembersihan. Alat-alat yang telah dibangunkan sebelum ini tidak mampu memenuhi kriteria sebagai pengesan minyak tertumpah secara berkesan. Jadi, kaedah dan sistem baru perlu diketengahkan untuk membantu dalam pengesanan tumpahan minyak. Projek ini membentangkan boyai yang dilengkapi dengan pengesan yang menggunakan tembaga dan mampu mengesan dan menghantar maklumat pada ketika berlakunya kemalangan minyak tertumpah dan pemasangannya adalah mudah. Kertas kerja ini menyentuh mengenai cara-cara pembikinan boyai dan pengesan minyak serta analisis dibuat pada boyai dan alat pengesan minyak. Aplikasi elektrolisis digunakan pada alat pengesan minyak, yang berdasarkan sifat kekonduksian elektrik oleh minyak dan air. Konsep aplikasi elektrolisis untuk pengesan minyak dibantu oleh Arduino UNO. Hasil daripada projek ini adalah boyai dicipta bersama pengesan minyak, kestabilan boyai dan penghasilan pengesan minyak di analisis serta boyai ini di uji dalam keadaan sebenar untuk mengesan minyak.